

## Time-Homogeneous Continuous-time Markov Chains

- Models process  $P$  moving between states over time
  - Assumes Markov property: only depends on current state
  - Assumes time-homogeneity: no dependence on time
- Transition probabilities for a given time duration specified through rate matrix  $Q$
- Hitting time: time until the process reaches some fixed subset of states  $A$

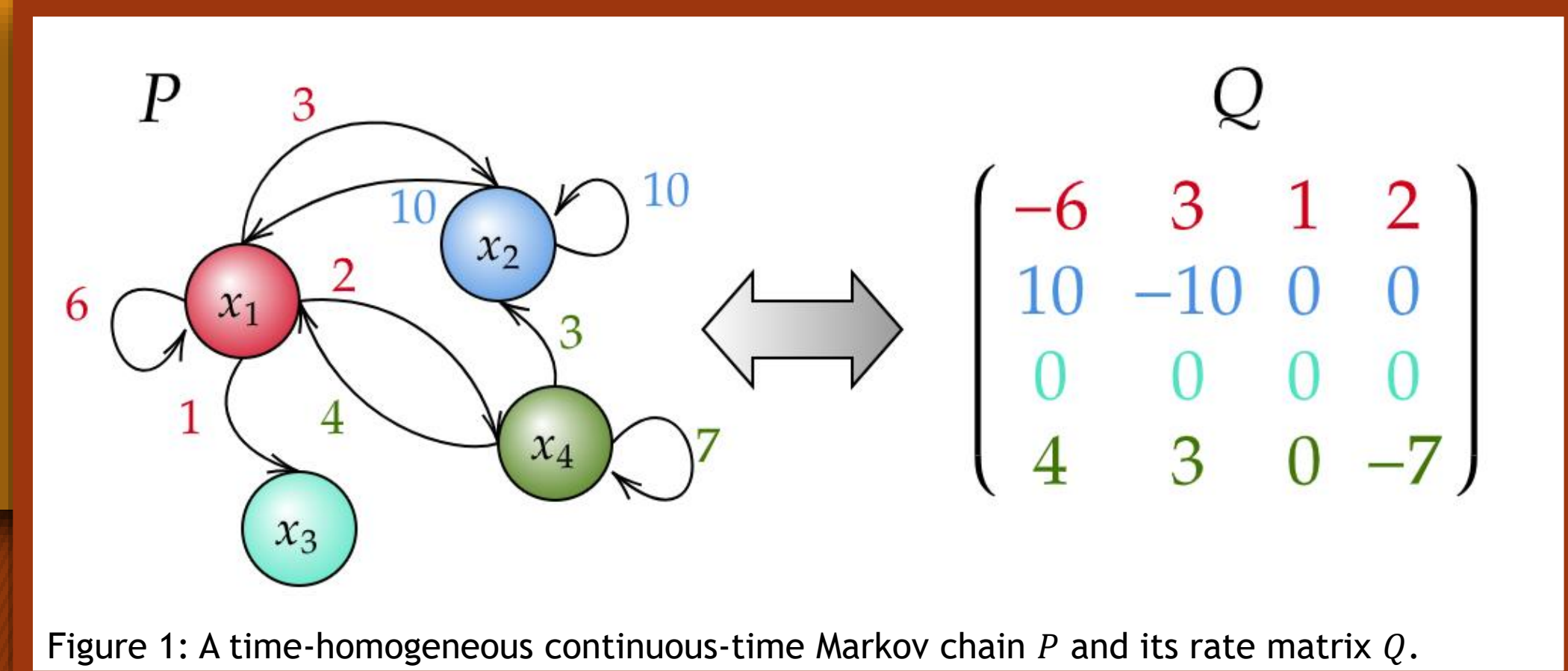


Figure 1: A time-homogeneous continuous-time Markov chain  $P$  and its rate matrix  $Q$ .

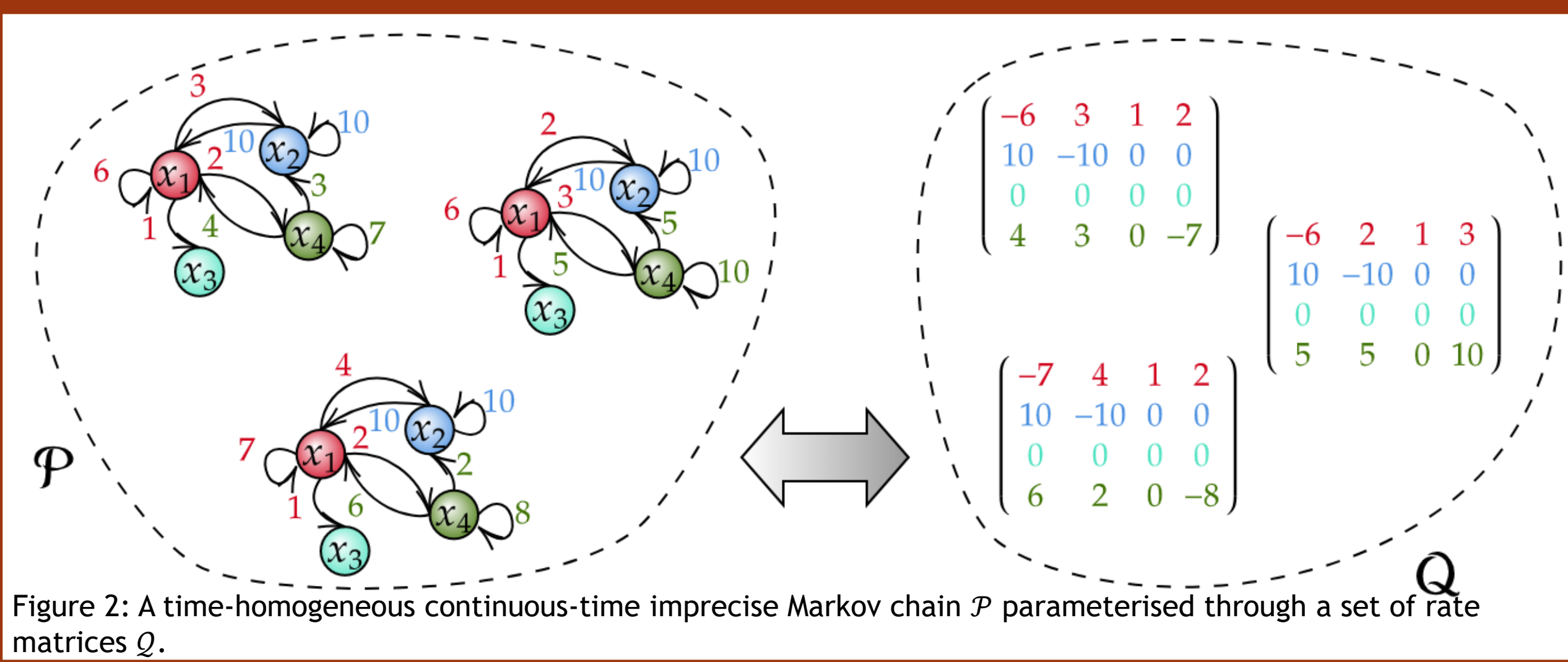


Figure 2: A time-homogeneous continuous-time imprecise Markov chain  $\mathcal{P}$  parameterised through a set of rate matrices  $Q$ .

## Imprecise Markov Chains

- Consider instead of a single process, a set of processes  $\mathcal{P}$ , parameterised by a set of rate matrices  $Q$
- Can contain three types of processes:
  - Markovian & time-homogeneous
  - Markovian, but not necessarily time-homogeneous
  - General processes

- More robust to structural assumptions: do not need to know whether the process is Markovian or time-homogeneous
- More robust to parameter uncertainty: no longer need to precisely specify  $Q$ !
- Compute upper and lower bounds (upper and lower expectations) for desired inferences
  - Considers all processes in  $\mathcal{P}$ , without weighting them

## State-of-the-Art [1]

- The upper and lower expected hitting times are the same for all three types of imprecise Markov chains
  - Can use computational inference tools suited for one specific type for all three types!
- Expected hitting times can be computed by solving a relatively simple non-linear system of equations

### Problem:

- Previous results currently assume that the probability of eventually hitting the set of states under consideration must be greater than 0, which results in a bounded hitting time.

[1] T. Krak. "Computing Expected Hitting Times for Imprecise Markov Chains". In: International Conference on Uncertainty Quantification & Optimisation. Springer, 2020, pp. 185-205.

## Our Contribution

- Divided the states into three classes.
- When starting in these classes:
  - $\mathcal{B}$ : zero lower probability to reach  $A$
  - $\mathcal{U}$ : non-zero lower probability to reach  $A$ , but non-zero upper probability to reach  $\mathcal{B}$
  - $\mathcal{Z}$ : remaining states
- $\mathcal{Z}$  essentially behaves independently from  $\mathcal{B}$  and  $\mathcal{U}$  and this subspace satisfies the original assumption of Krak's work
  - Recovered previous results for both upper and lower expected hitting times
- $\mathcal{B}$  and  $\mathcal{U}$  have been shown to have infinite upper expected hitting times for all three types of imprecise Markov chain
- $\mathcal{B}$  and  $\mathcal{U}$  have been shown to have infinite lower expected hitting times for all three types of imprecise Markov chain, provided that a weaker assumption than Krak's assumption is met:
  - The reachability behaviour of all  $Q \in \mathcal{Q}$  with respect to  $A$  is assumed to be similar

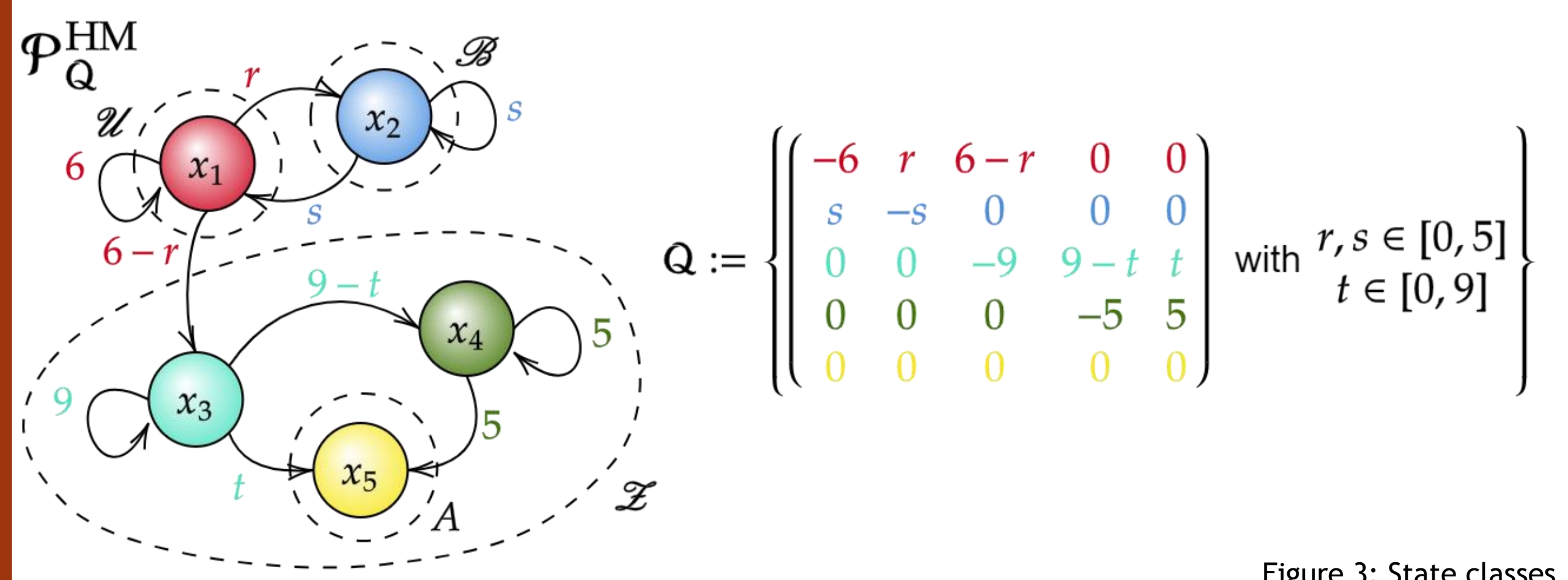


Figure 3: State classes